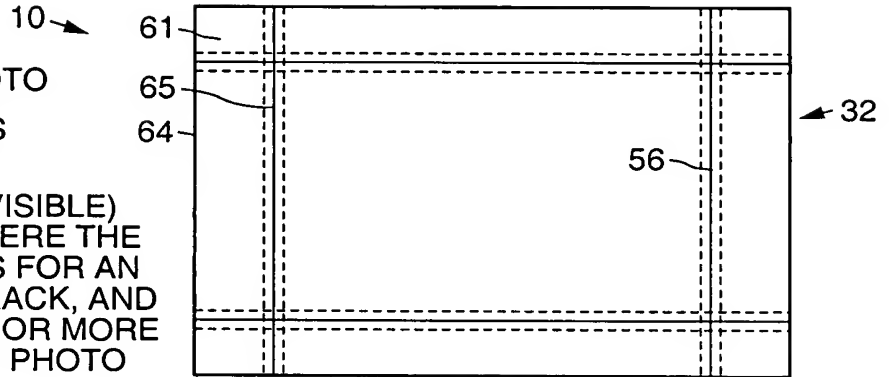


Fig. 4a

A USER TAKES A PHOTO

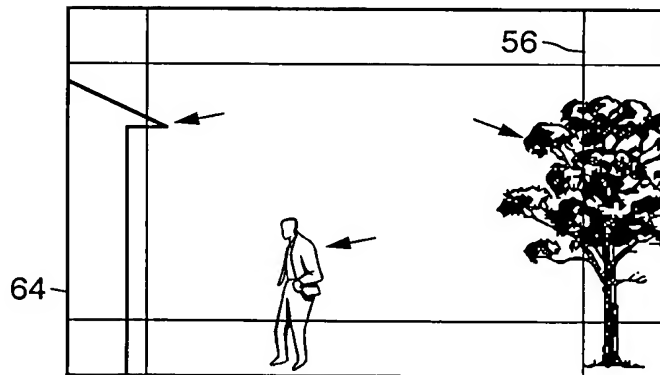
SOLID GUIDE LINES
ARE DISPLAYED

DOTTED LINES (NOT VISIBLE)
INDICATE REGIONS WHERE THE
ALGORITHM SEARCHES FOR AN
EDGE OR OBJECT TO TRACK, AND
TRIES TO IDENTIFY ONE OR MORE
ON EACH SIDE OF THE PHOTO

**Fig. 4b**

ARROWS (NOT VISIBLE
TO THE USER) INDICATE
POTENTIALLY USEFUL
EDGES FOR TRACKING

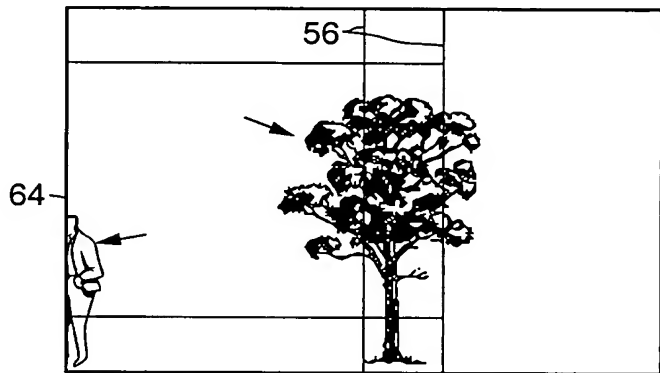
10 →

**Fig. 4c**

GUIDELINES ARE MOVED WITH
THE LIVE IMAGE AS THE USER
MOVES THE CAMERA TO SET
UP FOR THE NEXT PHOTO

ARROWS INDICATE THE
LOCATIONS THAT ARE
TRACKED BY THE ALGORITHM

10 →

**Fig. 4d**

THE USER PLACES THE
OVERLAPPING REGION
CORRECTLY AT THE EDGE
BY PUTTING THE LINES
ALONG THE CORRECT SIDE

10 →

